

Dynamic Treewidth in Logarithmic Time

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UNIVERSITY OF
COPENHAGEN

IBS DIMAG seminar

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Dynamic graph algorithms

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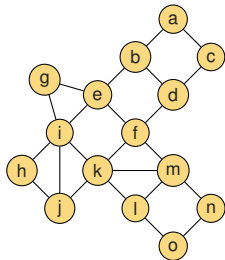
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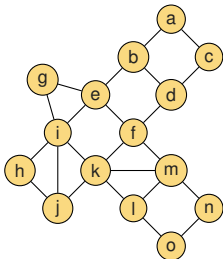
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4. [Henzinger&King'99]: $\mathcal{O}(\log^3 n)$ amortized time

Treewidth

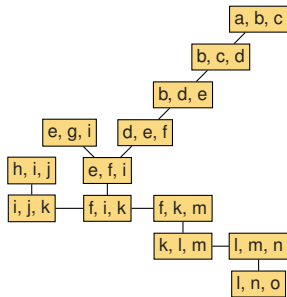


Graph G

Treewidth

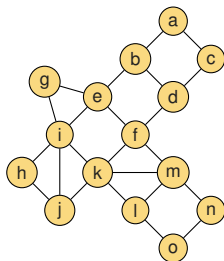


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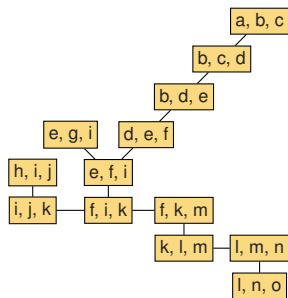


A tree decomposition of G

Treewidth



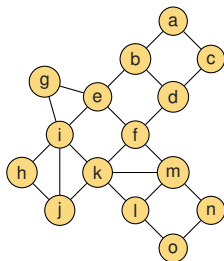
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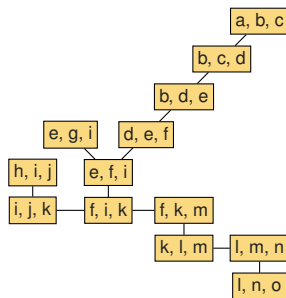
A tree decomposition of G

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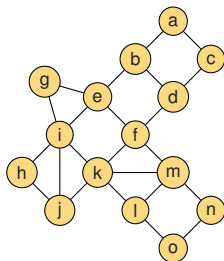
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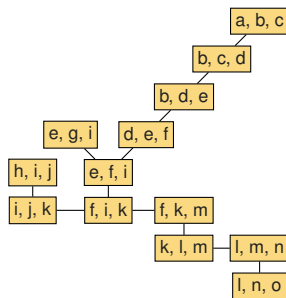
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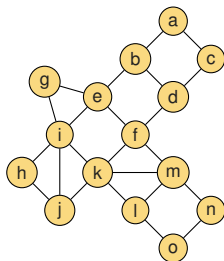
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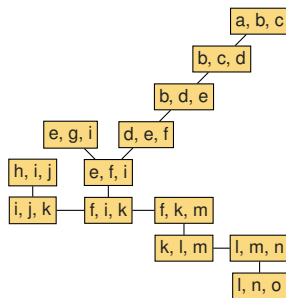
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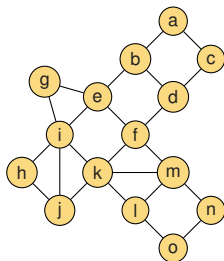
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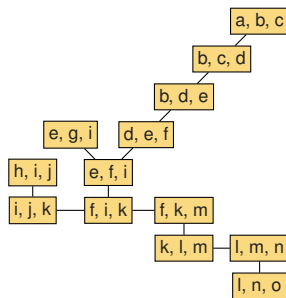
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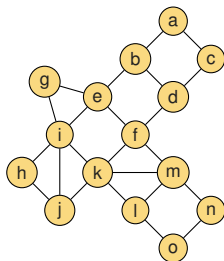


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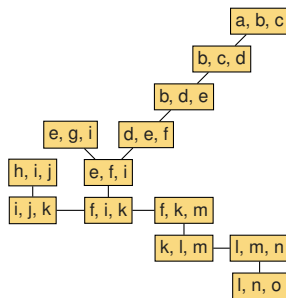
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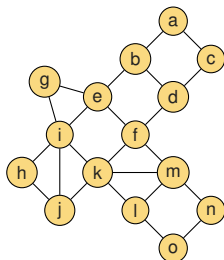


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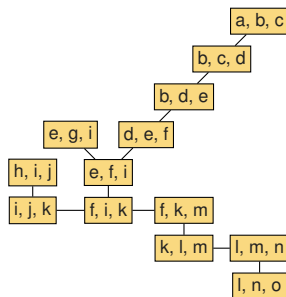
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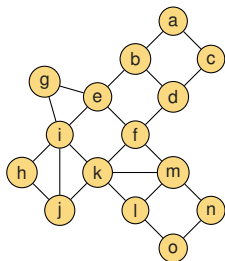
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Treewidth 2



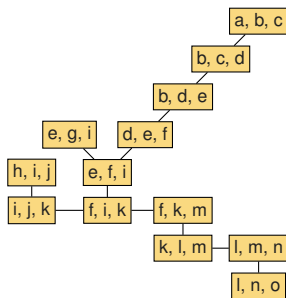
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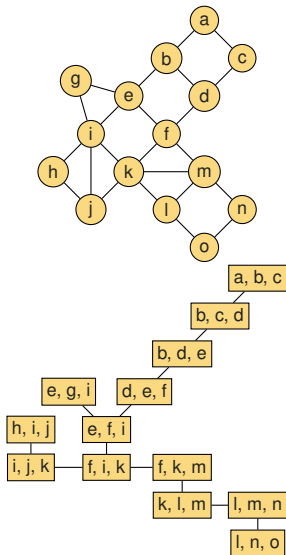
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[Robertson & Seymour'84, Arnborg & Proskurowski'89, Bertele & Brioschi'72, Halin'76]

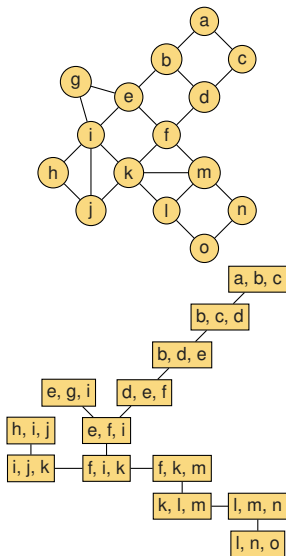
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- Algorithms for **trees** often generalize to algorithms for graphs of **small treewidth**



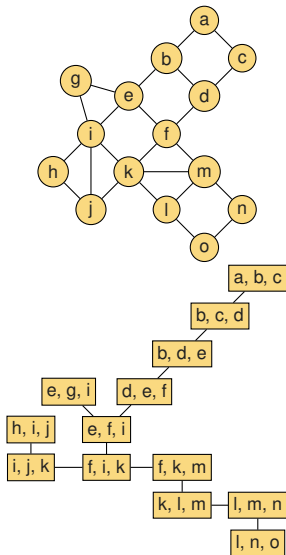
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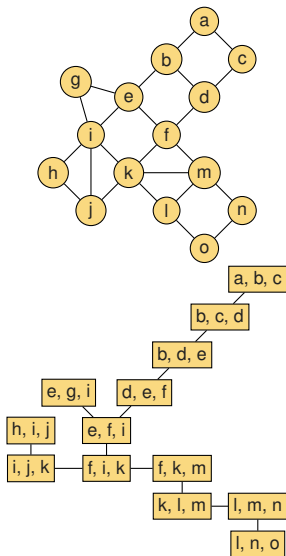
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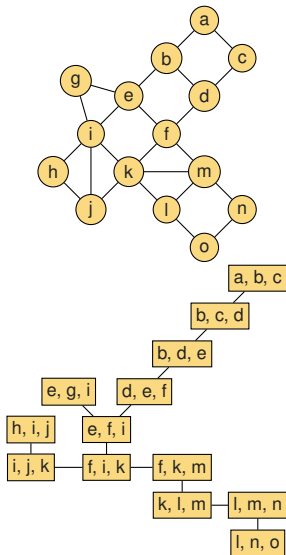
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- Need the tree decomposition!
- $2^{\mathcal{O}(k^3)} n$ time algorithm to compute an optimum-width tree decomposition [Bodlaender '96]
- $2^{\mathcal{O}(k)} n$ time for 2-approximation [K. '21]
- $n^{\mathcal{O}(1)}$ time for $\mathcal{O}(\sqrt{\log k})$ -approximation [Feige, Hajiaghayi, Lee'08]



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Theorem (This work)

$2^{\mathcal{O}(k)} \log n$ amortized update time 9-approximate tree decomposition.

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- ⇒ Dynamic Courcelle's theorem in $f(k) \cdot \log n$ amortized update time

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- $f(k) \cdot m^{1+o(1)}$ time algorithm for k -disjoint paths and H -minor-containment [K., Pilipczuk, Stamoulis, '24]

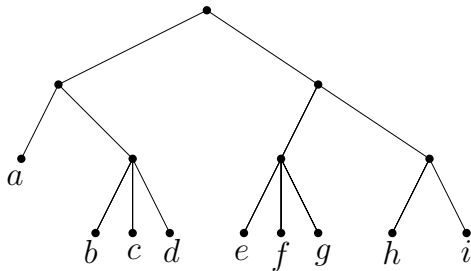
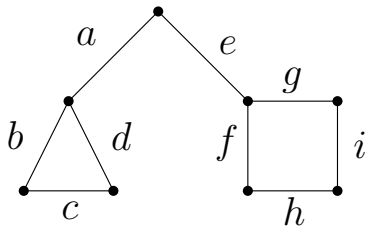
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- $f(k) \cdot m^{1+o(1)}$ time algorithm for k -disjoint paths and H -minor-containment [K., Pilipczuk, Stamoulis, '24]
- Dynamic rankwidth \Rightarrow rankwidth in $f(k) \cdot n^{1+o(1)} + \mathcal{O}(m)$ time [K., Sokolowski, '24]

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- Dynamic kernelization with $\mathcal{O}(\log n)$ amortized update time, e.g., for planar dominating set [Bertram, Haun, Jensen, K., '25]

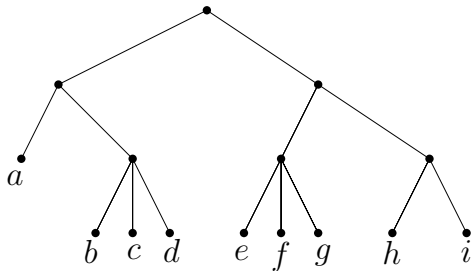
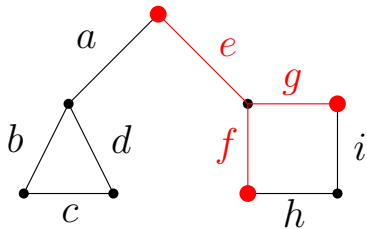
The algorithm

Maintained decomposition



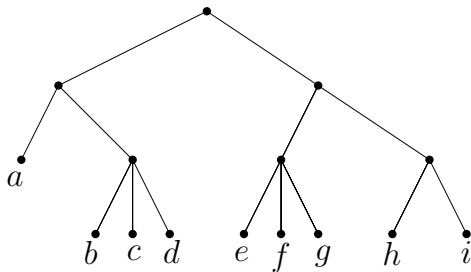
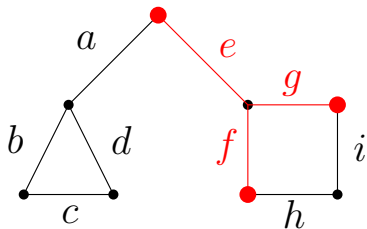
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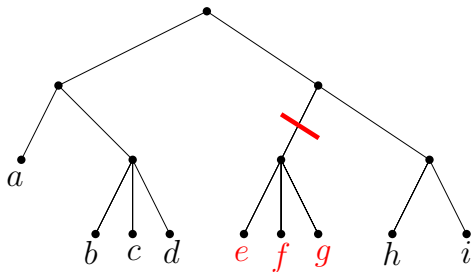
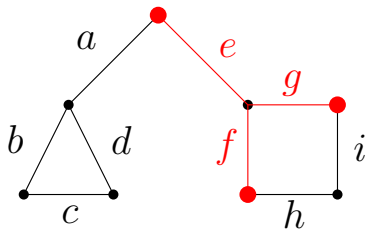
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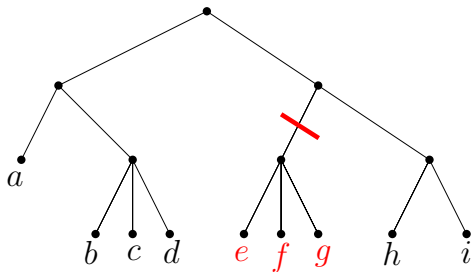
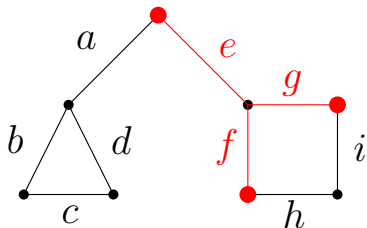
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- **Boundary** $\partial(F)$ of a set of edges $F \subseteq E$: The vertices incident to edges from both F and $E \setminus F$.
- A set of edges $F \subseteq E$ is **well-linked** if it cannot be partitioned to (C_1, C_2) so that $|\partial(C_1)| < |\partial(F)|$ and $|\partial(C_2)| < |\partial(F)|$

Maintained decomposition



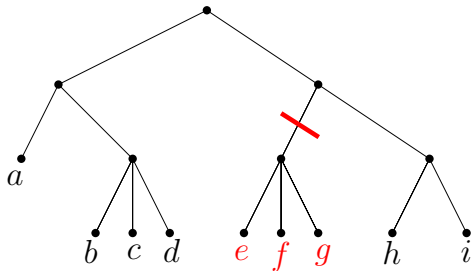
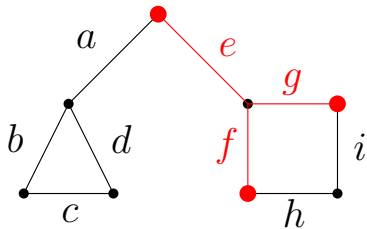
- **Branch decomposition:** Rooted tree whose leaves correspond to the edges of the graph
- **Boundary** $\partial(F)$ of a set of edges $F \subseteq E$: The vertices incident to edges from both F and $E \setminus F$.
- A set of edges $F \subseteq E$ is **well-linked** if it cannot be partitioned to (C_1, C_2) so that $|\partial(C_1)| < |\partial(F)|$ and $|\partial(C_2)| < |\partial(F)|$
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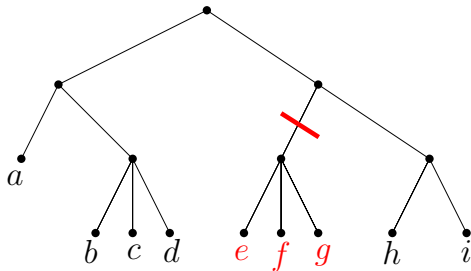
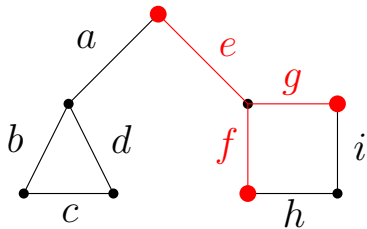
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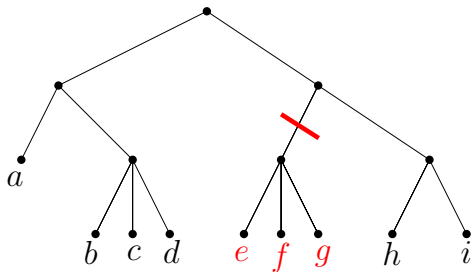
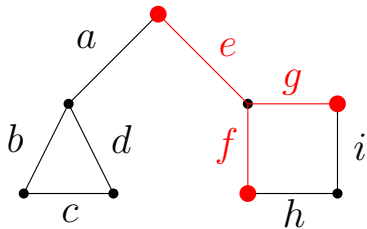
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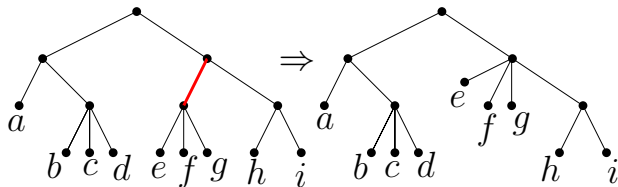


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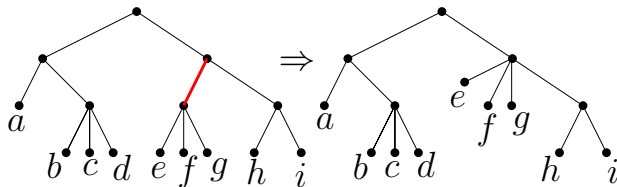
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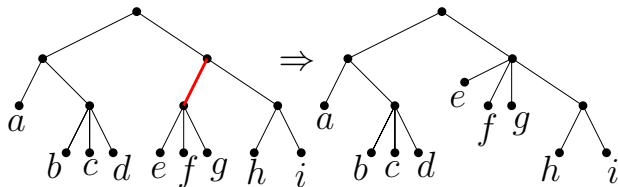
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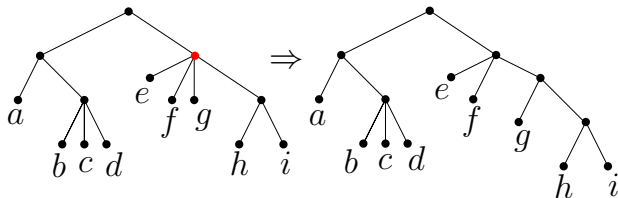
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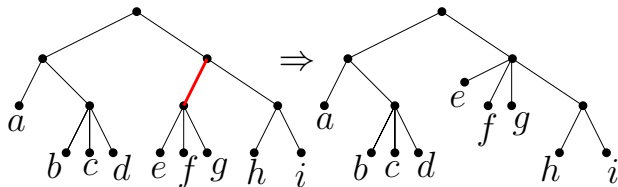
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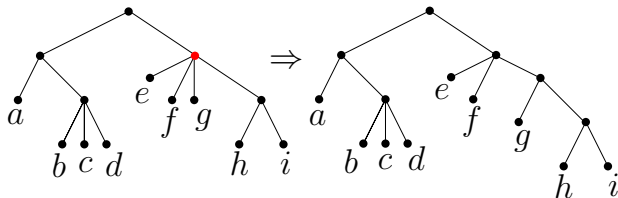
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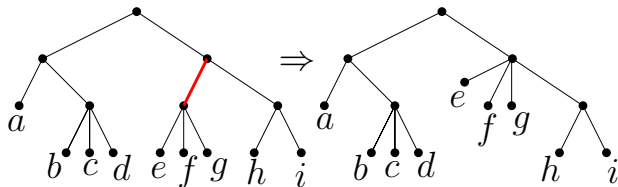
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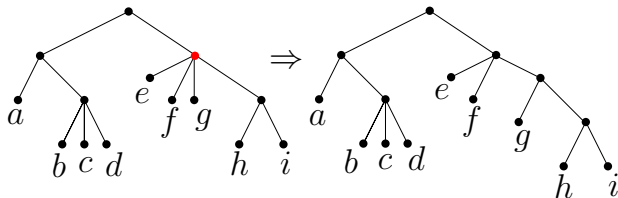
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- Can choose a set of ≤ 3 children that will not drop deeper



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Edge insertion and deletion increase $\Phi(T)$ by $2^{\mathcal{O}(k)} \log n$

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